

Tutorial: Setting up ADF4158 PLL

Hsiang-Yi Chung

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This tutorial is about how to set up the ADF4158 Direct Modulation/Waveform Generating, 6.1 GHz Fractional-N Frequency Synthesizer to output a continuous triangular waveform centered at 4 GHz with a bandwidth of 160 MHz as shown in Figure 1.

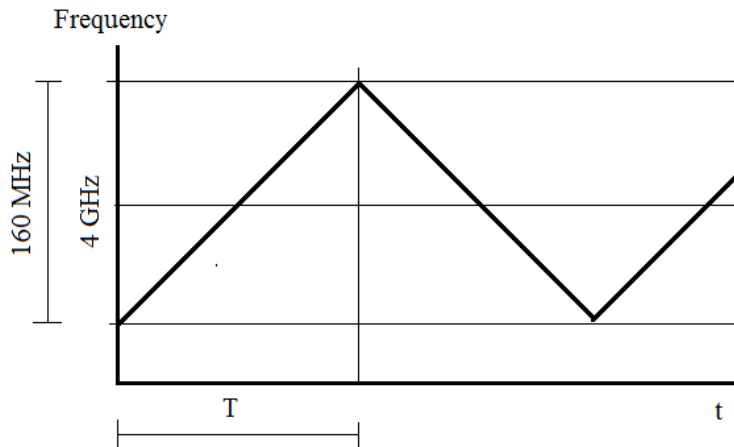


Figure 1: the above figure shows the desired output of the VCO after setting up the PLL.

The following are the values needed to be calculated:

- R
- T
- D
- INT
- FRAC
- $f_{DEV}$
- DEV
- DEV\_OFFSET
- CLK1
- CLK2
- Number of steps

In order to find R, T, D, INT, and FRAC, the following two equations are needed.

$$RF_{out} = f_{PFD} * INT + f_{PFD} * \frac{FRAC}{2^{25}} \quad (1)$$

$$f_{PFD} = REF_{in} * \left( \frac{1 + D}{R * (1 + T)} \right) \quad (2)$$

First of all, you will need to know the value of your  $REF_{in}$ , which is the frequency of the oscillator reference. The PLL can take in  $REF_{in}$  range from 10 MHz to 260 MHz, but  $f_{PFD}$  has a maximum of 32 MHz. The purpose of D, R, and T is to adjust the oscillator reference to a phase detector frequency less than 32 kHz. D doubles the oscillator reference frequency, T divides the oscillator reference frequency by two, and R divides the oscillator reference frequency by a value between 1 and 32. In our radar design, 40 Mhz of  $REF_{in}$  was used, so  $R = 1$ ,  $T = 1$ , and  $D = 0$ , which results in  $f_{PFD} = 20$  MHz from equation 2.

Then you will need to set the  $RF_{out}$  to the lowest frequency of the triangular wave, which is 3.96 GHz. In order to set  $RF_{out}$ , find the value of INT such that  $f_{PFD} * INT$  is closest but lower than or equal to your desired  $RF_{out}$ . Then use equation 1 to calculate the FRAC value. In our case, 3.96 GHz is divisible by 20 MHz ( $f_{PFD}$ ), which leads to  $INT = 192$  and  $FRAC = 0$ ;

The following shows how to calculate for CLK1, CLK2, number of steps, and  $f_{DEV}$ .

$$f_{RES} = \frac{f_{PFD}}{2^{25}} \quad (3)$$

$$t_{step_{min}} = \frac{1}{f_{RES}} \quad (4)$$

$$t_{step} = CLK1 * CLK2 * t_{step_{min}} \quad (5)$$

$$number\ of\ steps = \frac{T}{t_{step}} \quad (6)$$

$$f_{DEV} = \frac{BW}{number\ of\ steps} \quad (7)$$

$t_{step_{min}}$  is the minimum time PLL needs to step from one frequency to the next, so  $t_{step}$  is a multiple of  $t_{step_{min}}$ . Using equation 5, choose the appropriate values of CLK1 and CLK2 to get the desired  $t_{step}$ . In our case, we chose  $t_{step} = t_{step_{min}} = 50ns$ , so  $CLK1 = CLK2 = 1$ . Then

from equation 6 and using  $T = 0.7\text{ms}$ , number of steps = 14000, and from equation 7,  $f_{DEV} = 5714\text{ Hz}$ .

The following equations are needed to calculate DEV and DEV\_OFFSET.

$$f_{DEV} = \frac{f_{PFD}}{2^{25}} * DEV * 2^{DEV\_OFFSET} \quad (8a)$$

$$DEV\_OFFSET = \frac{\log_{10}\left(\frac{f_{DEV}}{f_{RES} * DEV_{max}}\right)}{\log_{10}(2)} \quad (8b)$$

First you will need to calculate  $DEV\_OFFSET$  using equation 8b by setting  $DEV_{max} = 2^{15}$  and use the values you calculated before. After you calculated for  $DEV\_OFFSET$ , plug the value into equation 8a to find DEV.

After calculating all these values, follow the timing diagram on the datasheet to set the corresponding registers to the desired values.

